

Exo 1: (E1) E.D. a coef. ch $x = \frac{1}{3}$ est 1 sol particulière

$P(x) = 2x^2 - 5x + 3 = 2(x-1)(x-\frac{3}{2})$ Sol de (E1) $y(x) = \frac{1}{3} + K_1 e^x + K_2 e^{\frac{2}{3}x}$

(E2) Posons $\tilde{z}(u,v) = \tilde{z}(x+ay, y) = \varphi(x,y)$

$\frac{\partial \varphi}{\partial x} = \frac{\partial \tilde{z}}{\partial u}$ $\frac{\partial \varphi}{\partial y} = a \frac{\partial \tilde{z}}{\partial u} + \frac{\partial \tilde{z}}{\partial v}$

φ est sol de (E2) $\Leftrightarrow 2 \frac{\partial \tilde{z}}{\partial u} + a \frac{\partial \tilde{z}}{\partial u} + \frac{\partial \tilde{z}}{\partial v} = 3 \tilde{z} \Leftrightarrow \frac{\partial \tilde{z}}{\partial v} = 3 \tilde{z} \Leftrightarrow \tilde{z}(u,v) = k(u) e^{3v}$

Les sol. de (E2) sont les fonctions de la forme $\varphi(x,y) = K(x-2y) e^{3y}$
 $\varphi(t, \phi) = K(t) e^{3t} = \cos t$ donc $K(t) = \cos t \cdot e^{-3t}$ Finalement $\varphi(x,y) = \cos(x-2y) e^{3(x-y)}$

Exo 2: $\Phi(u,v) = P \Leftrightarrow \begin{cases} u+v=3 \\ u^2+v^2=5 \end{cases} \Leftrightarrow \begin{cases} u+v=3 \\ v^2=1 \end{cases} \Leftrightarrow \begin{cases} u+v=3 \\ v=\pm 1 \end{cases} \Leftrightarrow \begin{cases} u=2 \\ v=1 \end{cases}$ $P = \Phi(2,1)$

2.2 $\Phi(u,v) = \Phi(2,1) + \frac{\partial \Phi}{\partial u}(2,1)(u-2) + \frac{\partial \Phi}{\partial v}(2,1)(v-1) + o(\|v-2, v-1\|) = 2(u-2) + (v-1) + o(\|v-2, v-1\|)$

Le plan tangent à $\text{Im } \Phi$ en P est $\text{Im } L$ avec $L(u,v) = (u-2) \begin{pmatrix} 1 \\ 4 \end{pmatrix} + (v-1) \begin{pmatrix} 1 \\ -2 \end{pmatrix} + P$.

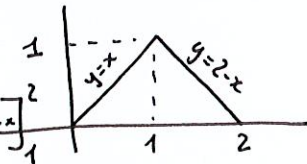
Les vecteurs $\left(\begin{pmatrix} 1 \\ 4 \end{pmatrix}; \begin{pmatrix} 1 \\ -2 \end{pmatrix} \right)$ forment une base du plan tangent à Σ en P .

2.3 $\vec{n} = \begin{pmatrix} 1 \\ 4 \end{pmatrix} \wedge \begin{pmatrix} 1 \\ -2 \end{pmatrix} = \begin{pmatrix} -6 \\ 2 \end{pmatrix}$ est un vecteur normal à Σ .

Equation du plan tangent à Σ en P : $-8(x-3) + 3(y-5) - (z-3) = 0$.

Exo 3: $I = \int_0^1 \int_0^x \frac{1}{1+x} dy dx + \int_1^2 \int_0^{2-x} \frac{1}{1+x} dy dx$

$= \int_0^1 \frac{x}{1+x} dx + \int_1^2 \frac{2-x}{1+x} dx = \int_0^1 1 - \frac{1}{1+x} dx + \int_1^2 \frac{3}{1+x} - 1 dx = [x - \ln(1+x)]_0^1 + [3 \ln(1+x) - x]_1^2$



$= -\ln 2 + 3 \ln 3 - 3 \ln 2 = 3 \ln 3 - 4 \ln 2 = \ln \left(\frac{27}{16} \right)$

Exo 3.2: $A = \iint_D 1 dx dy = \iint_D \frac{\partial Q}{\partial x} dx dy = \left| \int_{\partial D} Q(x,y) dy \right|$ avec $Q(x,y) = x$.
 $= \left| \int_0^1 (t - t^3)(1-2t) dt \right| = \left| \int_0^1 t - 2t^2 - t^3 + 2t^4 dt \right| = \left| \frac{1}{2} - \frac{2}{3} - \frac{1}{4} + \frac{2}{5} \right| = \left| \frac{30-40-15+24}{60} \right| = \frac{1}{60}$

Exo 4: $\vec{CD} = (2,2)$ $\vec{n} = \left(\frac{1}{\sqrt{2}}; \frac{-1}{\sqrt{2}} \right)$ $\|\vec{CD}\| = \sqrt{8}$

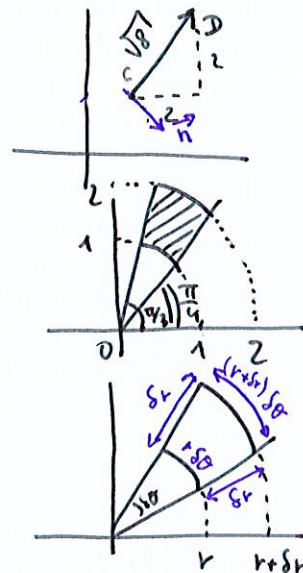
4.1: $F = (\psi_1 \vec{i} + \psi_2 \vec{j}) \cdot \left(\frac{1}{\sqrt{2}} \vec{i} - \frac{1}{\sqrt{2}} \vec{j} \right) \sqrt{8} = 2(\psi_1 - \psi_2)$

4.2: $\vec{\Phi} = \Phi(\tilde{x}; \tilde{y}) + \frac{\partial \Phi}{\partial x}(\tilde{x}; \tilde{y})(x-\tilde{x}) + \frac{\partial \Phi}{\partial y}(\tilde{x}; \tilde{y})(y-\tilde{y}) + o(\|x-\tilde{x}; y-\tilde{y}\|)$

4.3: $F = -\psi_r(r \delta \theta) - \psi_\theta \delta r + (r+\delta r) \delta \theta \psi_r + \delta r \psi_\theta$
 4.4: $= \psi_r \delta r \delta \theta$

- 4.5: $\text{sum } ① -\psi_r(r, \tilde{\theta}) r \delta \theta$
- $\text{sum } ② -\psi_\theta(\tilde{r}, \tilde{\theta}) \delta r$
- $\text{sum } ③ \psi_r(r+\delta r, \tilde{\theta}) (r+\delta r) \delta \theta$
- $\text{sum } ④ \psi_\theta(\tilde{r}, \tilde{\theta} + \delta \theta) \delta r$

$F = (\psi_r(r+\delta r, \tilde{\theta}) - \psi_r(r, \tilde{\theta})) r \delta \theta + \psi_r(r+\delta r, \tilde{\theta}) \delta r \delta \theta + [\psi_\theta(\tilde{r}, \tilde{\theta} + \delta \theta) - \psi_\theta(\tilde{r}, \tilde{\theta})] \delta r$
 $= \frac{\partial \psi_r}{\partial r} \cdot \delta r r \delta \theta + \psi_r \delta r \delta \theta + \frac{\partial \psi_\theta}{\partial \theta} \delta \theta \delta r$
 $= \left(\frac{\partial \psi_r}{\partial r} + \frac{1}{r} \psi_r + \frac{1}{r} \frac{\partial \psi_\theta}{\partial \theta} \right) \underbrace{r \delta \theta \delta r}_{\text{aire de } R_S}$



Pourquels des cotés de R_S .

